second base portion of the device, wherein the second base portion includes a second device electrical contact;

moving a first clamp of the device, attached to the first base portion, from an open position to a closed position, wherein in the closed position, the first base portion limits movement of the first UAV toward the device and the first clamp encloses an upper side of the first UAV electrical contact and limits movement of the first UAV electrical contact of the first UAV away from the first device electrical contact of the device; and

moving a second clamp of the device, attached to the second base portion, from an open position to a closed position, wherein in the closed position, the second base portion limits movement of the first UAV toward the device and the second clamp encloses an upper side of the second UAV electrical contact and limits movement of the second UAV electrical contact of the second UAV away from the second device electrical contact of the device.

18. The UAV of claim **4**, further comprising computer-executable instructions to:

execute a fourth authentication process prior to docking with the vehicle, wherein the fourth authentication process includes providing information from the UAV to the vehicle to authenticate the UAV to the vehicle.

19. The UAV of claim **18**, wherein providing the information from the UAV to the vehicle includes moving the UAV in a movement pattern for authentication by the vehicle.

20. The method of claim **11**, wherein the correspondence between the speed of the device and the docking speed supported by the first UAV by:

determining the speed of the vehicle;

determine docking speeds supported by a plurality of UAVs; and

determining that the first UAV supports a docking speed greater than or equal to a speed of the device.

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