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19. The multi-axis prosthetic ankle of claim 17, wherein said elastomeric material is a polymer rubber.

20. The multi-axis prosthetic ankle of claim 1, wherein said elastomeric material is casing having an enlargement located circumferentially opposite the toe of the prosthetic foot when the bottom component is connected to the prosthetic foot.

21. The multi-axis prosthetic ankle of claim 3, wherein the at least one mechanical stop is comprised by a compression resistance of said elastomeric material.

22. The multi-axis prosthetic ankle of claim 21, wherein the elastomeric material is a polymer rubber having a shore hardness A of between 50 and 99.

23. The multi-axis prosthetic ankle of claim 21, wherein the at least one stop permits Internal/External rotation of $\pm 11E$ to $15E$; Plantar flexion of $13E$ to $15E$; Dorsi flexion of $13E$ to $15E$; Inversion/Eversion of $\pm 5E$ to $10E$; Anterior/

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Posterior translation of ± 0.10 to 0.375 inches; Media/Lateral translation of t 0.05 to 0.250 inches; and Vertical displacement of 0.030 to 0.375 inches.

24. A multi-axis prosthetic ankle comprising:

a bottom component adapted to be connected to a prosthetic foot;

a lower leg connection component adapted to be connected to a prosthetic lower leg;

an elastomeric material securely connecting said bottom component with said lower leg connection component; and

rigid mechanical means bonded and suspended in said elastomeric material for limiting a deformation of said elastomeric material.

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