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said confirming step is received from said projective-capacitive sensor.

21. The method of claim 20, wherein said force sensor threshold is a force amplitude.

22. The method of claim 20, wherein said force sensor threshold is a frequency spectrum. 5

23. The method of claim 20, wherein said force sensor threshold setting step comprises applying a frequency filter to said detected force.

24. The method of claim 11, further comprising the steps of: 10

comparing a first touch position determined by said at least one force sensor with a second touch position determined by said projective-capacitive sensor; and returning said touchscreen system to a stand-by mode if an offset between said first and second touch positions is greater than a predetermined offset threshold. 15

25. The method of claim 11, further comprising the steps of:

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determining a background mechanical noise level; and

comparing said background mechanical noise level with a noise threshold, wherein said set of position coordinates is generated by said at least one force sensor if said background mechanical noise level is less than said noise threshold, and wherein said set of position coordinates is generated by said projective-capacitive sensor if said background mechanical noise level is greater than said noise threshold.

26. The method of claim 11, further comprising the step of determining if said touchscreen system is operating in a drag mode, wherein said set of position coordinates is generated by said at least one force sensor if said touchscreen system is not operating in said drag mode, and wherein said set of position coordinates is generated by said projective-capacitive sensor if said touchscreen system is operating in said drag mode.

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