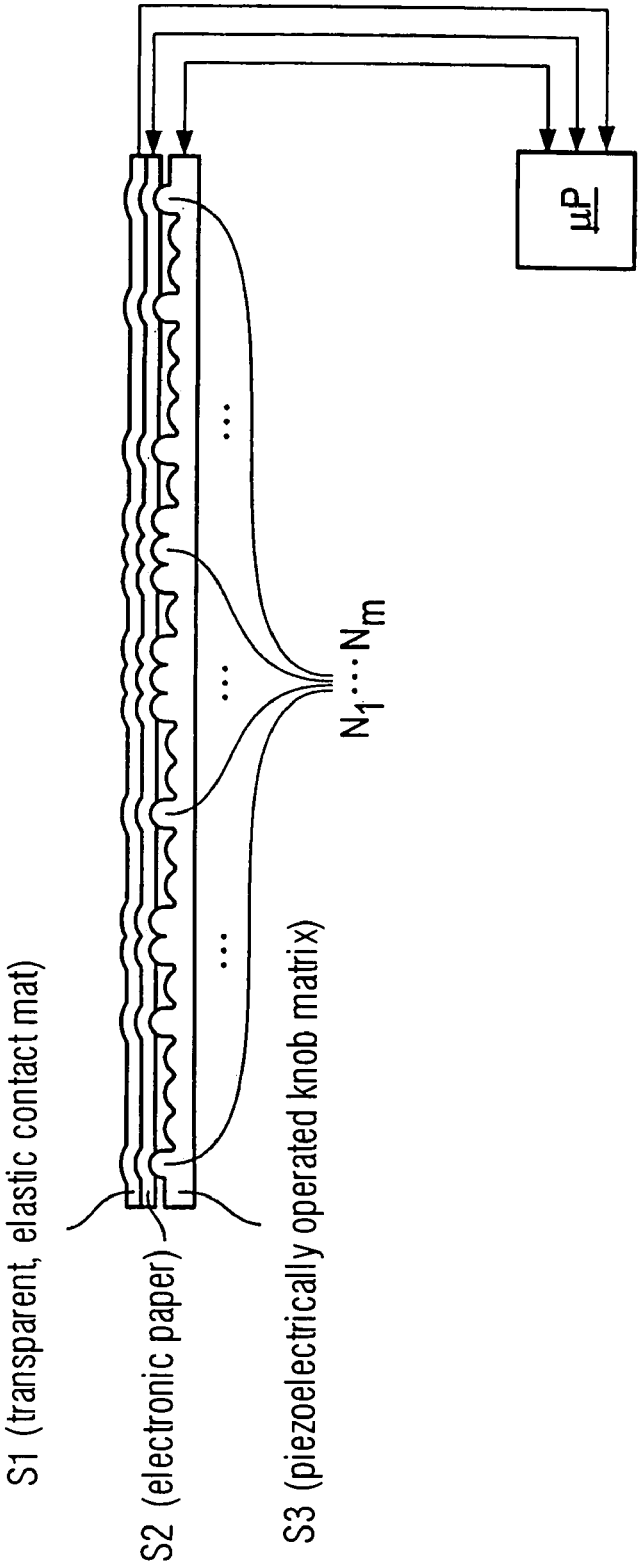
Sole Figure


S1 (transparent, elastic contact mat)
S2 (electronic paper)
S3 (piezoelectrically operated knob matrix)
$N_1 \cdots N_m$
µP