displaying the movement of the contact point in real-time on the display as the tibial prosthetic component is rotated;

measuring the rotation of the tibial prosthetic component wherein the rotation is measured with an inertial sensor in the insert; and

displaying a rotation value of the insert.

16. The method of claim **15** further including a step of fixing the tibial prosthetic component to the bone.

17. The method of claim **15** further including a step of calculating alignment of a leg including the rotation value.

18. The method of claim **15** further including a step of measuring alignment of a leg after rotation of the insert to change the contact point.

19. A system for adjusting a contact point of a muscular-skeletal joint comprising:

a tibial prosthetic component configured to rotate after being coupled to a tibia;

an insert configured to couple to the tibial prosthetic component wherein a plurality of load sensor couple to a surface of the insert, wherein the insert includes electronic circuitry coupled to the load plurality of sensors, an inertial sensor, and a power source, wherein the electronic circuitry is configured to control a measurement process and transmit measurement data and wherein a reference position is established between the tibial prosthetic component or insert to the tibia;

a processor configured to receive measurement data from the insert; and

a display coupled to the processor wherein the display is configured to display the surface of the insert, wherein the display is configured to display a contact point corresponding to an applied load to the surface, wherein movement of the contact point due to rotation of the tibial prosthetic component is displayed in real-time, wherein the inertial sensor is configured to measure a rotation value of the tibial prosthetic component, and wherein the rotation value is displayed on the display.

20. The system of claim **19** wherein the reference position corresponds to a rotation value of zero and wherein the display displays a value of zero when the tibial prosthetic component or insert are aligned to the tibia in the reference position.

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