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3. The device of claim 1, wherein the touch surface is a flexible touch sensitive surface, wherein the flexible touch sensitive surface is made of gel materials.

4. The device of claim 1, wherein the touch surface is a flexible wave transmittable touch pad.

5. The device of claim 1, wherein the first event includes a depression on the touch surface by a finger.

6. The device of claim 1, wherein the first event includes a depression on the touch surface by a stylus.

7. The device of claim 1, wherein the first plurality of haptic actuators are coupled to perimeter of the touch surface and configured to generate and send haptic waves to an interactive point.

8. The device of claim 1, wherein the first plurality of haptic actuators are configured to generate and send multiple haptic waveform pulses to an interactive point, wherein the haptic waveform pulses arrive at the interactive point at substantially same time.

9. The device of claim 1, wherein the second plurality of haptic actuators are configured to generate and send multiple canceling haptic waveform pulses to cancel various unwanted haptic waveform pulses on the touch surface.

10. The device of claim 1, wherein the touch surface is further configured to sense a second event; and wherein the first plurality of haptic actuators are configured to generate haptic feedback to the touch surface in response to the second event.

11. The device of claim 1, wherein the first and second plurality of actuators include one or more types of haptic elements.

12. A method of providing haptic feedback, comprising: detecting a first interaction on a flexible surface; determining a first location on the flexible surface in response to the first interaction; calculating a first distance from a first haptic actuator to the first location and a second distance from a second haptic actuator to the first location; and activating the first haptic actuator to generate a first haptic waveform pulse in response to the first distance and the second haptic actuator to generate a second haptic waveform pulse in response to the second distance to generate haptic feedback at the first location.

13. The method of claim 12, further comprising: monitoring a flexible surface; and calculating a third distance from a third haptic actuator to the first location and a fourth distance from a fourth haptic actuator to the first location.

14. The method of claim 13, further comprising activating the third haptic actuator in response to the third distance and the fourth haptic actuator in response to the fourth distance to cancel unwanted haptic effect on the flexible surface.

15. The method claim 12, further comprising: detecting a second interaction on the flexible surface;

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determining a second location on the flexible surface in response to the second interaction; calculating a fifth distance from a fifth haptic actuator to the second location and a sixth distance from a sixth haptic actuator to the second location; and

activating the fifth haptic actuator in response to the fifth distance and the sixth haptic actuator in response to the sixth distance to generate haptic feedback at the second location.

16. The method of claim 15, further comprising: calculating a seventh distance from a seventh haptic actuator to the second location; and activating the seventh haptic actuator in response to the seventh distance to minimize unwanted haptic effect on the flexible surface.

17. The method of claim 13, wherein monitoring a flexible surface includes sensing one of a contact, a movement, a predefined temperature, a light, and a predefined audible sound.

18. The method of claim 12, wherein detecting a first interaction on the flexible surface includes sensing a depression by a pointed object on the flexible surface.

19. The method of claim 12, wherein determining a first location on the flexible surface includes identifying physical coordinates of a contact point with respect to the flexible surface.

20. The method of claim 12, wherein activating the first haptic actuator in response to the first distance further includes generating a haptic wave traveling through medium of the flexible surface to generate haptic feedback at the first location.

21. A method of providing haptic feedback, comprising: detecting a first interaction at a first location on a flexible surface; generating a plurality of haptic waveform pulses with a first plurality of actuators to provide haptic feedback to the first location on the flexible surface in response to the detecting; and generating a plurality of canceling haptic waveform pulses with a second plurality of actuators to minimize unwanted haptic effects on the flexible surface at locations other than the first location.

22. The method of claim 21, further comprising calculating a first distance from at least one of the first plurality of haptic actuators to the first location prior to said generating the plurality of haptic waveform pulses to determine which of the first plurality of actuators to actuate; and calculating a second distance from at least one of the second plurality of haptic actuators to the first location prior to said generating the plurality of canceling haptic waveform pulses to determine which of the second plurality of actuators to actuate.

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