

the tube 20 (FIGS. 1, 3 and 6). The sample is then continually pumped and the program waits for a pump count change at 133. The maximum pump count was predetermined based on the head of the previous sample or measured by the user and entered into the program before the user began the pump (not shown) in the configure sequence 150 (FIG. 18).

The program 110 then goes through a series of steps at 139 starting with determining if the maximum pump count has been exceeded in the step 161. If the maximum pump count has been exceeded, the program will save the information indicating that no liquid was detected at 151 and proceed to the series of steps 153 of stopping the pump. During shutdown of the pump, the program shuts the pump off at 155 and returns to the calling routine at 157.

If the maximum pump count has not been exceeded at 161, it is then determined whether a good water count was found at 143. The program determines if a water count is received so near to the beginning of a sample drawing run as to indicate an error. This can occur in the first few cycles such as for example four cycles of the pump. After a predetermined number of cycles of the pump, this type of error tends not to occur. In the preferred embodiment, the pump must have counted at least 50 counts before the count is considered good. If it was not a good water count, the program: (1) returns to waiting for the pump count at 133; and (2) maintains in memory the amount of water counts already received and adds a new water count to the previously received water counts.

If it was a good water count, it is then determined if a new maximum amount of water counts should be calculated at 145. If a new maximum should be made, the program calculates a new maximum water count at 149, using the head from the previous sample or the head defined by the user in the head subsequence 196 (FIG. 24), and then decides at 147 if the sample water count is the correct amount. If not enough sample was pumped, the program returns to the wait for the pump count at 133 and pumps more liquid until it has pumped a predetermined amount of pump counts and continues with the series of steps 139 starting at 161 to determine if the maximum count was exceeded. If the pump did receive a correct water count, it is recorded in memory at 159 that the sample volume was delivered correctly and proceeds with the series of steps 153 of shutting down the pump at 155 and returning to the calling routine at 157.

If it is not necessary to calculate the maximum water count, then the program skips the step 149 and determines at this point if it is a correct water count at 147, records that the sample volume was delivered correctly at 159 and proceeds with the series of steps 153 of shutting off the pump at 155 and returning to the calling routines at 157.

When the program returns to the calling routine at 157, the memory is accessed to find out if the liquid was detected at 112 (FIG. 25) and if it was not, the program would advance to the program at 128 to access 170 of the options for the liquid detector control 162 (FIG. 19) of the configure sequence 150 to find out if it should retry pumping sample before shutting down. If the user entered any retries, and the total amount of retries has not been met, then the program returns to purging the pre-sample at 98 and continuing with the rinse routine 100 (FIG. 25).

In FIG. 27, there is shown a flow diagram of the program and run review sequence 221 (FIG. 18). The program and run review sequence 221 is used to check program setting or sampling routine results. The subsequences included are the pump tubing warning subsequence 225 and the sample information for the last sample routine subsequence 223.

Each time the pump count maximum for replacing the tubing is exceeded, the pump tubing warning message at 225 is displayed. The threshold for the pump count maximum has been user-defined in the tubing life indicator control 154 at 156 (FIG. 20) before beginning the pump. If the user does not enter a new threshold, the threshold from the previous sampling process will be used.

After each sample gathering process, certain information is stored in memory for future use at 223. Included are: (1) if the sample process was performed and no liquid was detected at 227; (2) the time and date at 229; and (3) the number of pump counts before liquid was detected at 231 and the amount of time for the entire pump cycle. The number of counts before liquid was detected at 231 is used to calculate the head at 149 (FIG. 26).

In FIG. 28, there is shown a block diagram of another embodiment of tubing life indicator circuit 154A for providing a signal after a predetermined number of strokes of roller against the tube 20 (FIGS. 1, 3 and 6) in the peristaltic pump assembly 16 (FIG. 1), having the cycle signal generator 11, a counter 241, a switch 247, a manually resettable switch 243 and a warning light 253. The counter 241 is directly connected to the conductor 13 to receive all counts regardless of direction and having an output set at a predetermined number of counts connected to the resettable switch 243 to actuate the switch at the predetermined number of counts and thus energize the warning light to which it is connected.

With this arrangement, the operator may set the counter 241 at a count that indicates the tube 20 (FIGS. 1, 3 and 6) should be replaced. When the number of pulses from the cycle signal generator 11 reaches the preset number, the counter 241 supplies a signal to the resettable switch 243 which applies a signal from the source of voltage 255 to the warning light 253. The resettable switch 243 can be manually reset when the tube is changed and it resets the counter 241 and disconnects the power 255 from the warning light 253.

To permit a hardware determination of the direction of rotation, the switch 247 receives pulses from the conductor 13 and a direction signal from the cycle signal generator 11 to switch from one of the two output conductors 249 or 251 to the other so that pulses representing the number cycles in each direction can be determined. This function can also be performed in software.

In FIG. 29, there is shown a functional flow diagram of the program for positioning the distributor arm including the step 452 of getting a request to deposit a sample at a particular location, calibrating the system, or updating the position indication of the distributor arm. With this arrangement, the position of the distributor arm is continually updated to ensure that any movement of the arm between intentional moves is tracked. A full rotation of the distributor arm results in 1200 state changes of the optical interruptors described in FIG. 18.

To calibrate the distributor arm, the step 454 of calibrating includes the steps 460 of moving to stop past the last bottle, the step 462 of moving to stop past the first bottle and calculating the total arm flexure, the step 464 of obtaining the time to go from bottle five to bottle one of the 24 bottle base as shown in step 464, the step 466 of getting the time to go from bottle 20 to bottle 24 of the 24 bottle base as shown in step 466, the step 468 of assigning a portion of the total arm flexure to the bottle one side, and the step 470 of moving to bottle one in the order stated. In this manner, a measure is taken of the air at the stop positions caused by